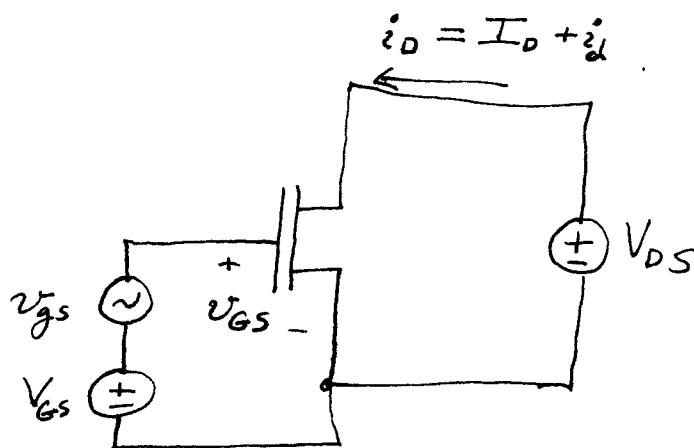


LOW FREQUENCY SMALL-SIGNAL (9.1.1)

I_0 SATURATION



DC: V_{DS} (U.C.)_{u.c}

AC: v_{ds} (L.C.)_{l.c}

TOTAL: v_{DS} (L.C.)_{u.c}

DC quantity $\gg$ AC quantity ($V_{GS} \gg v_{gs}$)
(small signal)

$$i_D = i_d + I_D = \frac{\beta}{2} \left(\underbrace{V_{GS} + v_{gs}}_{v_{GS}} - V_{THN} \right)^2 (1 + \lambda V_{DS})$$

A. TRANSCONDUCTANCE (g_m)

$$g_m = \left. \frac{\partial i_D}{\partial v_{GS}} \right|_{V_{GS}, I_D} = \beta (V_{GS} - V_{THN}) (1 + \lambda V_{DS})$$

(Evaluated at ~~the~~ D.C. bias point
@ Q = operating point)

$$\Delta i_D = g_m \Delta v_{GS}$$

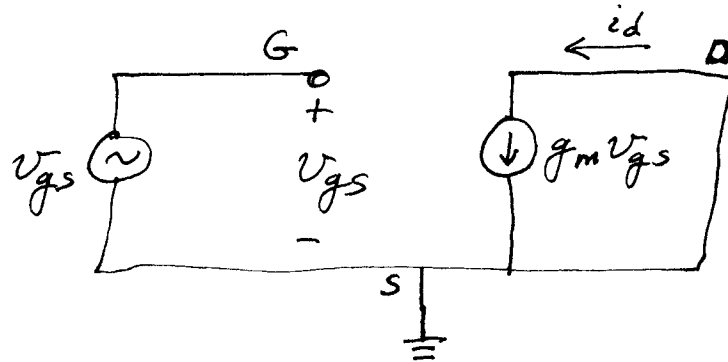
$$\left. \begin{aligned} \Delta i_D &\equiv i_d \\ \Delta v_{GS} &\equiv v_{gs} \end{aligned} \right\} \text{A.C. quantities}$$

$$\text{So } i_d = g_m v_{gs}$$

FOR $\lambda V_{DS} \ll 1$,

$$g_m = \beta (V_{GS} - V_{THN}) = \sqrt{2\beta I_D}$$

LOW FREQ SMALL SIGNAL CIRCUIT



Small-signal model is a 1st order (linear) expansion of non-linear model.

FOR v_{gs} too large $\Rightarrow$ non-linear effects
i.e. distortion, harmonics.

B. BODY TRANSCONDUCTANCE ($V_{SB} \neq 0$)

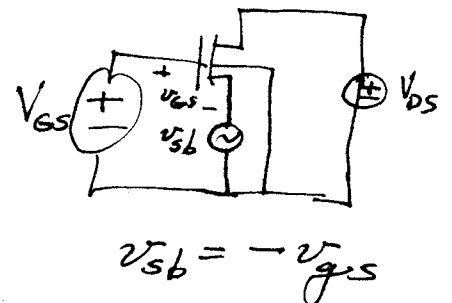
$$V_{TNN}(V_{SB}) = V_{THN0} + \gamma [\sqrt{2\phi_F + V_{SB}} - \sqrt{2\phi_F}]$$

$$g_{mb} = - \left. \frac{\partial i_D}{\partial V_{SB}} \right|_{V_{SB}, I_D}$$

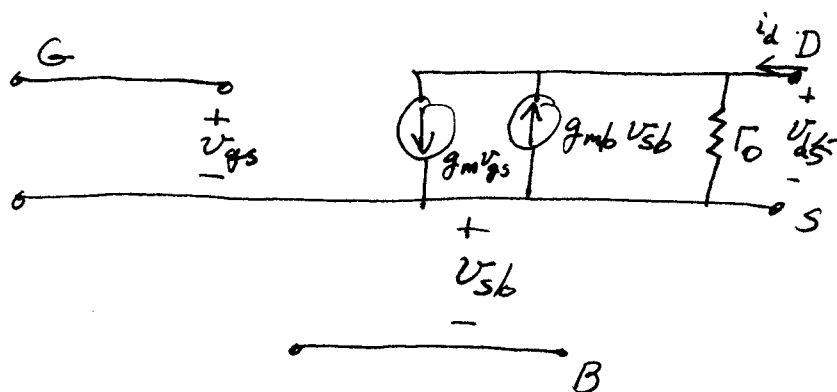
$$= - \frac{\partial i_D}{\partial V_{THN}} \frac{\partial V_{TNN}}{\partial V_{SB}}$$

$$= g_m \frac{\gamma}{2\sqrt{2\phi_F + V_{SB}}}$$

$$\equiv g_m \eta \quad (0 \leq \eta \leq 0.6)$$



$$i_d = g_m v_{gs} - g_{mb} v_{sb}$$



C. Input Resistance = ∞ (Low f)

$$\left(\frac{\partial i_g}{\partial v_{gs}} \right)^{-1}$$

D. Output Resistance (r_o) ---

$$r_o^{-1} = \left. \frac{\partial i_D}{\partial v_{DS}} \right|_{V_{GS}, I_D} = \frac{\beta}{2} (V_{GS} - V_{THN})^2 \lambda$$

$$\approx I_D \lambda \quad (\lambda V_{DS} \ll 1)$$

NOTE: λ often defined by an "Early Voltage" (V_A)

$$\lambda = \frac{1}{V_A}$$

$$r_o = \frac{1}{I_D \lambda} = \frac{V_A}{I_D}$$

E. VOLTAGE GAIN ($v_{sb} = 0$)

$$\frac{v_{ds}}{v_{gs}} = \frac{-g_m v_{gs} r_o}{v_{gs}} = -g_m r_o$$

II. TRIODE OR LINEAR REGION

$$I_D = \beta [(V_{GS} - V_{THN}) V_{DS} - V_{DS}^2 / 2]$$

Output RESISTANCE

$$R_{ch}^{-1} = \left. \frac{\partial i_D}{\partial V_{DS}} \right|_{V_{DS}, I_D} = \beta [V_{GS} - V_{THN} - V_{DS}]$$

$$R_{CH} = \frac{1}{\beta (V_{GS} - V_{THN} - V_{DS})}$$

FOR $V_{DS} \ll V_{GS} - V_{THN}$

$$R_{CH} = \frac{1}{\beta (V_{GS} - V_{THN})} = \frac{1}{g_m}$$

III. SUBTHRESHOLD (WEAK INVERSION)

$$I_D = I_{D0} \frac{W}{L} e^{q(V_{GS} - V_{THN}) / (NO \cdot k_B T)}$$

$$\frac{\partial I_D}{\partial V_{GS}}$$

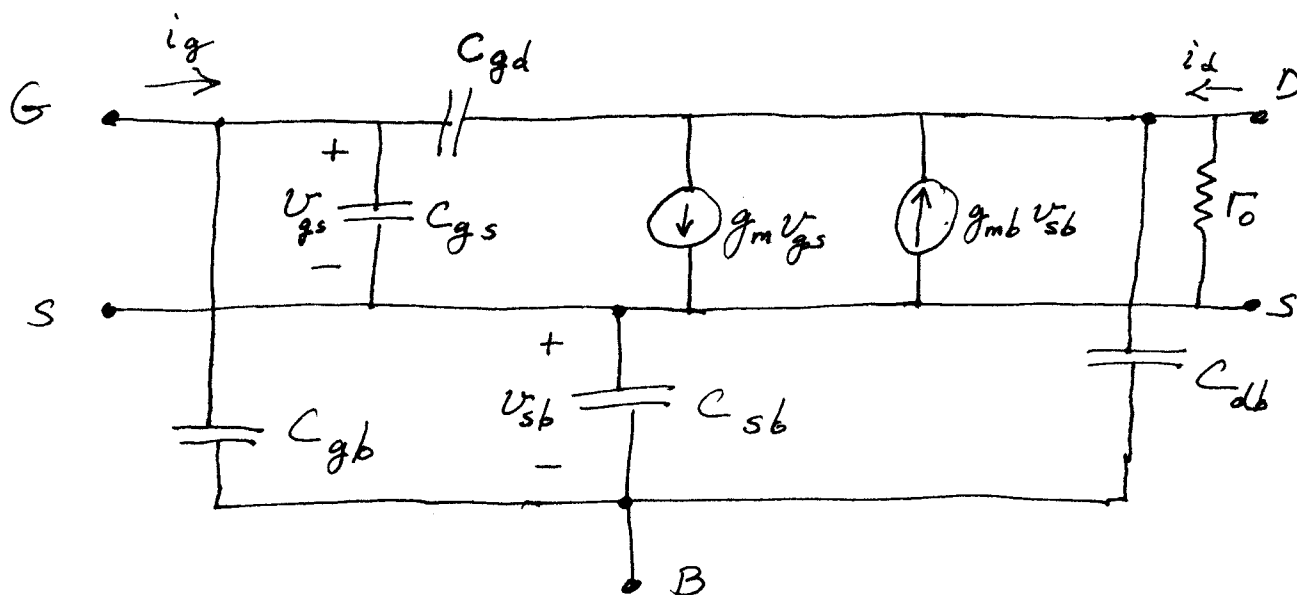
$$i_D = I_{D0} \frac{W}{L} e^{q(V_{GS} - V_{THN}) / (NO \cdot k_B T)}$$

$$g_m = \left. \frac{\partial i_D}{\partial V_{GS}} \right|_{V_{GS}} = \frac{I_D q}{NO \cdot k_B T} \quad \text{(same form as for a diode)}$$

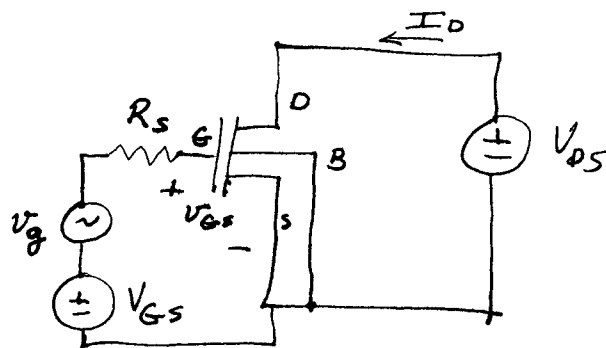
$$= \frac{I_D}{NO \cdot V_T}$$

$$V_T = \frac{k_B T}{q} = 26 \text{ mV} @ 300K$$

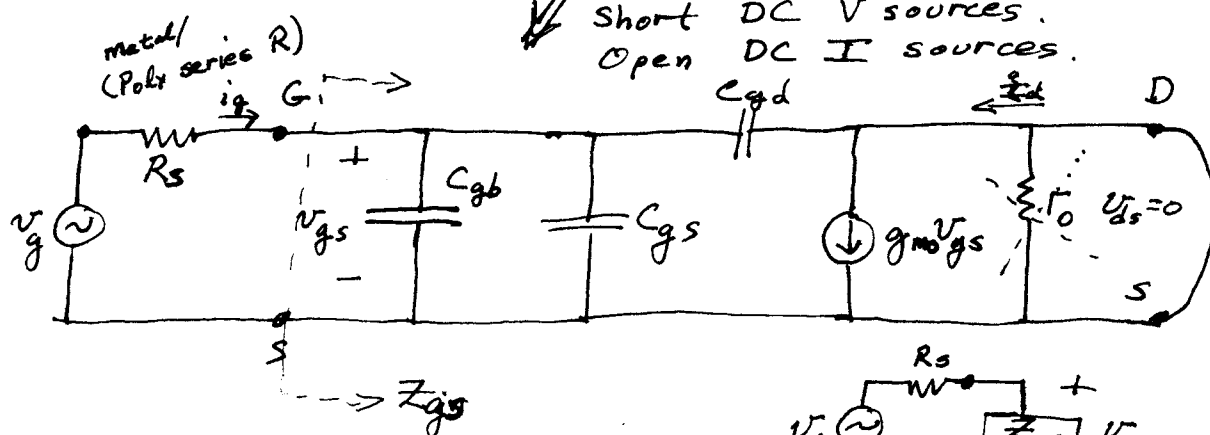
9.2 HIGH FREQUENCY SMALL SIGNAL



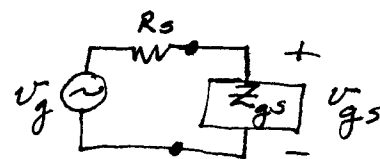
TRANS CONDUCTANCE $g_m(\omega)$



Short DC V sources.
Open DC I sources.



$$Z_{gs} = \frac{1}{j\omega(C_{gb} + C_{gs} + C_{gd})}$$



$$v_{gs} = v_g \frac{Z_{gs}}{R_s + Z_{gs}} = v_g \frac{\frac{1}{j\omega C_{TOT}}}{R_s + \frac{1}{j\omega C_{TOT}}}$$

$$v_{gs} = v_g \frac{1}{1 + j\omega R_s (C_{gb} + C_{gs} + C_{gd})}$$

~~$$g_m(\omega) = \frac{i_d}{v_g}$$~~

Assume that $|i_d| \gg |v_{gs} j\omega C_{gd}|$
(feedthrough negligible)

Then $i_d \cong g_{m0} v_{gs}$

$$g_m(\omega) \cong \frac{i_d}{v_g} = \frac{g_{m0}}{1 + j\omega R_s (C_{gb} + C_{gs} + C_{gd})}$$

For $R_s = 0$, $g_m(\omega) = g_{m0}$

$g_{m0} = \text{low freq. } g_m.$

CUTOFF FREQUENCY

The frequency when $\left| \frac{i_d}{i_g} \right| = 1$ (unity current gain)

AGAIN, Assuming

$$i_d \cong g_{m0} v_{gs} \gg |j\omega C_{gd} v_{gs}|$$

(Not always a great assumption)

$$\left| \frac{i_d}{i_g} \right| = \left| \frac{g_{m0} v_{gs}}{j\omega (C_{gb} + C_{gs} + C_{gd}) v_{gs}} \right| = 1$$

$$f_T = \frac{g_{m0}}{2\pi (C_{gb} + C_{gs} + C_{gd})}$$

$$C_{gs} \gg C_{gb}, C_{gd}$$

$$f_T \approx \frac{g_{mo}}{2\pi C_{gs}}$$

In saturation $C_{gs} = \frac{2}{3} W \cdot L \cdot C_{ox}$ (Table 5.1)

$$g_{mo} \approx \frac{\mu_n C_{ox}}{L} W (V_{GS} - V_{THN})$$

$$f_T \approx \frac{3\mu_n}{4\pi L^2} (V_{GS} - V_{THN}) \Rightarrow \text{minimum } L \text{ for max } f_T$$

9.3 Temperature Effects

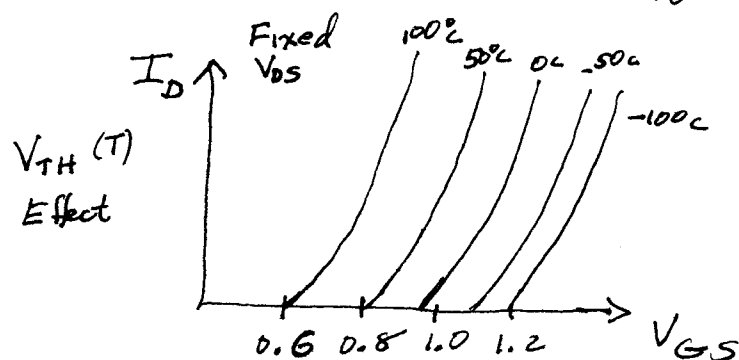
~~$$g_m(T)$$~~
$$I_D = \frac{\mu_n C_{ox} W}{2L} (V_{GS} - V_{THN})^2$$

$$\left. \begin{array}{l} V_{THN}(T) \\ \mu_n(T) \end{array} \right\} \Rightarrow I_D(T), g_m(T)$$

Temperature Coefficient of V_{THN}

$$TCV_{THN} = \frac{1}{V_{THN}} \frac{dV_{THN}}{dT} \approx -3000 \frac{\text{ppm}}{^\circ\text{C}} = \frac{-0.003}{^\circ\text{C}}$$

$$\mu(T) = \mu(T_0) \left(\frac{T}{T_0} \right)^{-1.5}$$



$V_{THN} \uparrow$ as $T \downarrow$